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This monograph collates the past decade's work on fractional models and fractional systems in the fields of analysis, robust control and path tracking. Themes such as PID control, robust path tracking design and motion control methodologies involving fractional differentiation are amongst those explored. It juxtaposes recent theoretical results at the forefront in the field, and applications that can be used as exercises that will help the reader to assimilate the proposed methodologies.

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The fractional order controller is presented as a generalization of the common PID controller. Then, it is shown how the first generation of the CRONE methodology is able to design robust...

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