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x2(I)dI = Ay1(t) + By2(t) where yi(t), i = 1;2, are the corresponding outputs to xi(t), i = 1;2. ii. If x(t) = u(t) then y(t) = r(t) the corresponding output is y1(t) = y(t). System is time-invariant. In general, if x1(t) = x(t) the output is 1 T Zt to T Zt to

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